Technical data sheet

FOR THE ROTARY ACTUATOR

HSI 11 S7

Type:



Type: HSL 11 SZ Art. no.: 3207109					
Model		Vane-type rotary actuator			
		In principle the actuation has a pressure- and viscosity-dependent internal leak volume flow rate. For example, if an external torque affect the rotary actuator shaft in an idle mode, the rotary actuator shaft			
		shifts slowly from its angle position! HSL: Rotary actuator as basic model without an end position damping and without an internal rotating			
		angle limitation.			
			•	uator can be equipped with components are adapted to the specific application,	
			such as:		
				ction plates with differnt hole patterns	
				es and rotary encoders of all well-known manufacturers Isation accumulators	
Size		. 11	labo ana pa		
Mounting style					
- Rotary actuator housing		-		unting with thread according to DIN 13-1 - M 24	
Drive shoft and		Strength class of the fastening screws \geq 8.8			
- Drive shaft end - Centre hole in the drive shaft end		involute spline shaft according to DIN 5480-W 170x5,0x32x 8f DIN 332-2 - D M 30			
Connection type		pipe thread according to DIN ISO 228-1;			
· · · · · · · · · · · · · · · · · · ·				he rear cylinder cover	
Installation position		arbitrary;	Depending	on the position of installation and case of application a load may cause running	
			-	ator drive shaft. In such a case, appropriate countermeasures must be taken!	
Installation instructions Rotary angle limitation	see operating instructions An external rotary angle limitation is recommended!				
Intended use				intended for generation an alternating torque in a stationary application.	
		,			
max. nominal pressure	p _{Nmax}	bar	120		
min. minimum pressure	p_{Mmin}	bar	15	Required for a proper functioning of the load-free drive.	
max. starting pressure without load	p _{St max}	bar	7.2	at an output pressure of p = 1 bar	
specific torque	M_{sp}	Nm/bar	468.81	torque constant	
theoretical torque	M th	Nm	56 257	at $\Delta p = p_{N max}$	
mechanical efficiency \approx	$\eta_{\text{ mec}}$	-	0.940	at $\Delta p = p_{N \max}$ and $\omega = \omega_{\max}$	
effective torque	M eff	Nm	52 882	at $\Delta p = p_{N max}$ and $\omega = \omega_{max}$	
number of working chambers	Z		2		
nominal angle of rotary	φN	grad	292	The internal stop must not be approached!	
max. operating angle of rotary	ϕ A max		290		
recom. min. operating angle of rotary	ϕ A min	grad	13	If smaler rotating angles are to be realised in continious operation, the manufacturer must be consulted.	
maximum radial force	Frmax	N	40 000	force acting centered on the journal of the drive shaft	
maximum axial force	Faxmax		20 000	force acting centrically on the journal of the drive shaft	
weight ≈	m	kg	760.0	± 10%, incl. oil filling	
mass moment of inertia of drive shaft	J _{W0}	kgm ²		± 5%, without other attachments such as hub, coupling, rotation encoder, etc.	
max. angular speed	ω _{max}	rad/s	0.9	This corresponds to 52 deg/s or an equivalent rotational speed of $n=9$ min ⁻¹ .	
specific displacement	V sp	cm ³ /°	81.82	This results in a theoretical operating volume of V_A = 23 728.6 cm ³ .	
theoretical volume flow rate required	Q th	l/min	253.3	at ω=ω max	
max. internal leakage volume flow rate	QLmax	l/min	0.88	at $\Delta p = p_{N max}$ and v=50 mm ² /s ³)	
effective required volume flow rate	Q eff	l/min	254.2	at $\Delta p = p_{N max}$, $\omega = \omega_{max}$ and $v = 50 \text{ mm}^2/\text{s}$ 3)	
permissible pressure fluid				HLP mineral oils according to DIN 51524 T2	
temperature range of pressure fluid	θöι	°C	-20-+80	The viscosity range set in operation is to be observed.	
range of kinematic viscosity	ν	mm²/s	18 – 150	short-term, the optimum operating viscosity range is $30 - 50 \text{ mm}^2/\text{s}$	
cleanliness class of pressure fluid				Max. permissible degree of pollution according to ISO 4406 class 18/16/13. To increase service life, we recommend according to ISO 4406 class 17/15/12.	
range of ambient temperature	θ	°C	0-+60		
design of component surfaces				metallic bright and wetted with anticorrosion agents	
				Subject to technical modifications and error	

Subject to technical modifications and error!

1) The simultaneous occurrence of two or more maximum values of temperature, pressure and angular speed requires the written consent of the manufacturer!

²) Theoretically determined value without manufacturing tolerances and if so an efficiency.

³) Median recorded in test series; an inferential variance is possible.

⁴) In mint condition of the internal seals and their counter-surfaces!

Page 1 of 1 V 1.0 2024-04-04 Technical data sheet Type : HSL 11 SZ Art. no. : 3207109 Hense Systemtechnik GmbH & Co. KG Flottmannstr. 55 D-44807 Bochum

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