Technical data sheet

FOR THE ROTARY ACTUATOR



Type: HSL 04 SZ Art. no.: 3207710					
Model		Vane-type rotary actuator In principle the actuation has a pressure- and viscosity-dependent internal leak volume flow rate. For example, if an external torque affect the rotary actuator shaft in an idle mode, the rotary actuator shaft			
Series		 shifts slowly from its angle position! HSL: Rotary actuator as basic model without an end position damping and without an internal rotating angle limitation. The rotary actuator can be equipped with components are adapted to the specific application, such as: Valve connection plates with differnt hole patterns Control valves and rotary encoders of all well-known manufacturers 			
0			Hubs and pu	llsation accumulators	
Size	•••••	04			
Mounting style		cindlo cid	lad faca mai	unting with thread according to DIN 12.1 M 12	
- Rotary actuator housing		single-sided face mounting with thread according to DIN 13-1 - M 12 Strength class of the fastening screws \geq 8.8			
- Drive shaft end		involute spline shaft according to DIN 5480-W 45x2,0x21x 8f			
- Centre hole in the drive shaft end		DIN 332-2 - D M 16			
Connection type		pipe thread according to DIN ISO 228-1;			
		A and B: G3/8; axial in the rear cylinder cover			
Installation position		arbitrary; Depending on the position of installation and case of application a load may cause running ahead the rotary actuator drive shaft. In such a case, appropriate countermeasures must be taken!			
Installation instructions		see operating instructions			
Rotary angle limitation		An external rotary angle limitation is recommended!			
Intended use	•••••	The rotary	/ actuator is	intended for generation an alternating torque in a stationary application.	
may nominal prossure	p _{Nmax}	bar	200	1)	
max. nominal pressure	•		15	,	
min. minimum pressure	р _{м min}			Required for a proper functioning of the load-free drive.	
max. starting pressure without load	p _{St max}		8.0	at an output pressure of p = 1 bar	
specific torque	M sp	Nm/bar	7.88	torque constant ²)	
theoretical torque	M th	Nm	1 576	at $\Delta p = p_{N max}$ ²)	
mechanical efficiency ≈	η _{mec}	-	0.960	at $\Delta p = p_{N max}$ and $\omega = \omega_{max}$ ³)	
effective torque	M_{eff}	Nm	1 513	at $\Delta p = p_{N max}$ and $\omega = \omega_{max}$ ³)	
number of working chambers	Z	-	2		
nominal angle of rotary	φN	grad	251	The internal stop must not be approached! ²)	
max. operating angle of rotary	ϕ_{Amax}	grad	250		
recom. min. operating angle of rotary	ϕ A min	grad	24	If smaler rotating angles are to be realised in continious operation, the manufacturer must be consulted.	
maximum radial force	F r max	Ν	3 500	force acting centered on the journal of the drive shaft	
maximum axial force	F _{ax max}	Ν	2 000	force acting centrically on the journal of the drive shaft	
weight ≈	m	kg	25.5	± 10%, incl. oil filling	
mass moment of inertia of drive shaft	Jwo	kgcm ²	37.11	± 5%, without other attachments such as hub, coupling, rotation encoder, etc.	
max. angular speed	ω_{max}	rad/s	11.9	This corresponds to 682 deg/s or an equivalent rotational speed of n= 114 min ⁻¹ . $^{-1}$)	
specific displacement	V sp	cm ³ /°	1.38	This results in a theoretical operating volume of V_A = 343.8 cm ³ . ²)	
theoretical volume flow rate required	Q_{th}	l/min	56.3	at $\omega = \omega_{\text{max}}$ ²)	
max. internal leakage volume flow rate	QLmax	l/min	0.21	at $\Delta p = p_{N max}$ and v=50 mm ² /s $^{3})^{4}$	
effective required volume flow rate	Q eff	l/min	56.5	at $\Delta p = p_{N max}$, $\omega = \omega_{max}$ and v=50 mm ² /s ³) ⁴)	
permissible pressure fluid				HLP mineral oils according to DIN 51524 T2	
temperature range of pressure fluid	θöι	°C	-20 - +80	The viscosity range set in operation is to be observed. ¹)	
range of kinematic viscosity	v	mm²/s	18 – 150	short-term, the optimum operating viscosity range is 30 – 50 mm ² /s	
cleanliness class of pressure fluid				Max. permissible degree of pollution according to ISO 4406 class 18/16/13. To increase service life, we recommend according to ISO 4406 class 17/15/12.	
range of ambient temperature	θ	°C	0-+60		
design of component surfaces				metallic bright and wetted with anticorrosion agents	
				Subject to technical modifications and error	

Subject to technical modifications and error!

1) The simultaneous occurrence of two or more maximum values of temperature, pressure and angular speed requires the written consent of the manufacturer!

²) Theoretically determined value without manufacturing tolerances and if so an efficiency.

³) Median recorded in test series; an inferential variance is possible.

⁴) In mint condition of the internal seals and their counter-surfaces!

Page 1 of 1 V 1.0 2024-04-04 Technical data sheet Type : HSL 04 SZ Art. no. : 3207710 Hense Systemtechnik GmbH & Co. KG Flottmannstr. 55 D-44807 Bochum

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