Technical data sheet

FOR THE ROTARY ACTUATOR

HSL 06 SP

Type:



Type: HSL 06 SP Art. no.: 3209626					
Model		Vane-type rotary actuator In principle the actuation has a pressure- and viscosity-dependent internal leak volume flow rate. For example, if an external torque affect the rotary actuator shaft in an idle mode, the rotary actuator shaft shifts slowly from its angle position!			
Series	HSL: Rotary actuator as basic model without an end position damping and without an internal rotating				
	angle limitation.				
			e rotary acti such as:	uator can be equipped with components are adapted to the specific application,	
		- \	/alve connec	ction plates with differnt hole patterns	
				es and rotary encoders of all well-known manufacturers	
Size		- H 06	lubs and pu	lsation accumulators	
Mounting style		00			
- Rotary actuator housing	single-sided face mounting with thread according to DIN 13-1 - M 16				
	Strength class of the fastening screws \geq 8.8				
- Drive shaft end	two parallel keys according to DIN 6885-1 - B20x12x 90 (2 x 180°)				
- Centre hole in the drive shaft end	DIN 332-2 - D M 20 nine thread according to DIN ISO 228.1:				
Connection type	pipe thread according to DIN ISO 228-1; A and B: G1/2; axial in the rear cylinder cover				
Installation position	arbitrary; Depending on the position of installation and case of application a load may cause running				
		-		ator drive shaft. In such a case, appropriate countermeasures must be taken!	
Installation instructions	see operating instructions				
Rotary angle limitation Intended use		, ,	(le limitation is recommended! intended for generation an alternating torque in a stationary application.		
		merotary			
max. nominal pressure	p _{Nmax}	bar	200	1	¹)
min. minimum pressure	p_{Mmin}	bar	15	Required for a proper functioning of the load-free drive.	
max. starting pressure without load	p _{St max}		8.0	at an output pressure of p = 1 bar	
specific torque	M sp	Nm/bar	28.31		²)
theoretical torque	M th	Nm	5 662		²)
mechanical efficiency ≈	η_{mec}	-	0.960		³)
effective torque	M eff	Nm	5 436	at $\Delta p = p_{N max}$ and $\omega = \omega_{max}$	3)
number of working chambers	Z	-	2	The internal stan must not be annuashed!	²)
nominal angle of rotary	φN	grad	274	The internal stop must not be approached!	-)
max. operating angle of rotary	φAmax	grad	270	If analysysteting angles are to be realized in continious anarction, the	
recom. min. operating angle of rotary	ϕ A min	grad	22	If smaler rotating angles are to be realised in continious operation, the manufacturer must be consulted.	
maximum radial force	Frmax	Ν	10 000	force acting centered on the journal of the drive shaft	
maximum axial force	Faxmax	Ν	5 000	force acting centrically on the journal of the drive shaft	
weight ≈	m	kg	78.0	± 10%, incl. oil filling	
mass moment of inertia of drive shaft	J _{W0}	kgdm ²	4.12	\pm 5%, without other attachments such as hub, coupling, rotation encoder, etc.	
max. angular speed	ω_{max}	rad/s	4.8	This corresponds to 275 deg/s or an equivalent rotational speed of n= 46 min ⁻¹ .	¹)
specific displacement	V sp	cm ³ /°	4.94	This results in a theoretical operating volume of V_A = 1 334.1 cm ³ .	²)
theoretical volume flow rate required	Q_{th}	l/min	81.6	at $\omega = \omega_{\text{max}}$	²)
max. internal leakage volume flow rate	$Q_{L\text{max}}$	l/min	0.35	at $\Delta p = p_{N max}$ and v=50 mm ² /s 3	
effective required volume flow rate	Q_{eff}	l/min	82.0	at $\Delta p = p_{N max}$, $\omega = \omega_{max}$ and v=50 mm ² /s ³) ⁴	4)
permissible pressure fluid				HLP mineral oils according to DIN 51524 T2	
temperature range of pressure fluid	θöι	°C	-20 – +80		¹)
range of kinematic viscosity	ν	mm²/s	18 – 150	short-term, the optimum operating viscosity range is 30 – 50 mm ² /s	
cleanliness class of pressure fluid				Max. permissible degree of pollution according to ISO 4406 class 18/16/13.	
range of ambient temperature	0	°C	0-+60	To increase service life, we recommend according to ISO 4406 class 17/15/12.	
design of component surfaces	θ	0	0 - F00	metallic bright and wetted with anticorrosion agents	
action of component surfaces				Subject to technical modifications and error!	į

Subject to technical modifications and error!

1) The simultaneous occurrence of two or more maximum values of temperature, pressure and angular speed requires the written consent of the manufacturer!

²) Theoretically determined value without manufacturing tolerances and if so an efficiency.

³) Median recorded in test series; an inferential variance is possible.

⁴) In mint condition of the internal seals and their counter-surfaces!

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