Technical data sheet

FOR THE ROTARY ACTUATOR

HSL 08 SP

Type:



Type: HSL 08 SP Art. no.: 3218091					
Model			e rotary actu		
		In principle the actuation has a pressure- and viscosity-dependent internal leak volume flow rate. For example, if an external torque affect the rotary actuator shaft in an idle mode, the rotary actuator shaft shifts slowly from its angle position!			
		HSL: Rotary actuator as basic model without an end position damping and without an internal rotating			
		angle limitation.			
			ne rotary act such as:	uator can be equipped with components are adapted to the specific application,	
		- Valve connection plates with differnt hole patterns			
				es and rotary encoders of all well-known manufacturers	
Size		- 1	huns and hu	llsation accumulators	
Mounting style		• -			
- Rotary actuator housing		single-sided face mounting with thread according to DIN 13-1 - M 20			
		Strength class of the fastening screws ≥ 8.8			
- Drive shaft end		two parallel keys according to DIN 6885-1 - B32x18x140 (2 x 180°) DIN 332-2 - D M 24			
- Centre hole in the drive shaft end Connection type		pipe thread according to DIN ISO 228-1;			
		A and B: G3/4; axial in the rear cylinder cover			
Installation position	arbitrary; Depending on the position of installation and case of application a load may cause running				
		ahead the rotary actuator drive shaft. In such a case, appropriate countermeasures must be taken!			
Installation instructions	see operating instructions An external rotary angle limitation is recommended!				
Rotary angle limitation Intended use			intended for generation an alternating torque in a stationary application.		
		,			
max. nominal pressure	р _{N max}	bar	160	1	
min. minimum pressure	p_{Mmin}	bar	15	Required for a proper functioning of the load-free drive.	
max. starting pressure without load	p _{St max}	bar	8.0	at an output pressure of p = 1 bar	
specific torque	M sp	Nm/bar	98.90	torque constant 2	
theoretical torque	M th	Nm	15 824	at ∆p=p _{Nmax} 2	
mechanical efficiency ≈	η_{mec}	-	0.950	at $\Delta p = p_{N max}$ and $\omega = \omega_{max}$	
effective torque	M eff	Nm	15 033	at $\Delta p = p_{N max}$ and $\omega = \omega_{max}$	
number of working chambers	Z	-	2	The internal star must not be environely all	
nominal angle of rotary	φN	grad	292	The internal stop must not be approached! 2	
max. operating angle of rotary	φAmax		290	If amplex veteting angles are to be verticed in continious apprection, the	
recom. min. operating angle of rotary	ϕ A min	grad	23	If smaler rotating angles are to be realised in continious operation, the manufacturer must be consulted.	
maximum radial force	Frmax	Ν	20 000	force acting centered on the journal of the drive shaft	
maximum axial force	Faxmax		10 000	force acting centrically on the journal of the drive shaft	
weight ≈	m	kg	245.0	± 10%, incl. oil filling	
	J _{wo}	kgdm ²	33.69	± 5%, without other attachments such as hub, coupling, rotation encoder, etc.	
max. angular speed	ω _{max}	rad/s	2.2	This corresponds to 126 deg/s or an equivalent rotational speed of $n=21 \text{ min}^{-1}$.	
specific displacement	V sp	cm ³ /°	17.26	This results in a theoretical operating volume of V_A = 5 005.8 cm ³ .	
theoretical volume flow rate required	Q _{th}	l/min	130.6	at w=w _{max} 2	
max. internal leakage volume flow rate	Q _{Lmax}	l/min	0.59	at $\Delta p = p_{N max}$ and v=50 mm ² /s ³) ⁴	
effective required volume flow rate	Q_{eff}	l/min	131.2	at $\Delta p = p_{N max}$, $\omega = \omega_{max}$ and $v = 50 \text{ mm}^2/\text{s}$ 3) ⁴	
permissible pressure fluid				HLP mineral oils according to DIN 51524 T2	
temperature range of pressure fluid	θöι	°C	-20-+80	The viscosity range set in operation is to be observed.	
range of kinematic viscosity	ν	mm²/s	18 – 150	short-term, the optimum operating viscosity range is $30 - 50 \text{ mm}^2/\text{s}$	
cleanliness class of pressure fluid				Max. permissible degree of pollution according to ISO 4406 class 18/16/13. To increase service life, we recommend according to ISO 4406 class 17/15/12.	
range of ambient temperature	θ	°C	0-+60		
design of component surfaces				metallic bright and wetted with anticorrosion agents	
				Subject to technical modifications and error	

Subject to technical modifications and error!

1) The simultaneous occurrence of two or more maximum values of temperature, pressure and angular speed requires the written consent of the manufacturer!

²) Theoretically determined value without manufacturing tolerances and if so an efficiency.

³) Median recorded in test series; an inferential variance is possible.

⁴) In mint condition of the internal seals and their counter-surfaces!

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